

# Appendix C

## Scaling differential equations

### C.1 What is scaling?

In this appendix we learn how to *scale*, or *non-dimensionalise*, a differential equation.

Consider a general differential equation

$$\frac{dx}{dt} = f(x). \quad (\text{C.1})$$

Suppose that we define a dimensionless variables  $x^*$  and  $t^*$  by

$$\begin{aligned} x^* &= \alpha x, \\ t^* &= \beta t. \end{aligned}$$

How do we obtain a differential equation for  $\frac{dx^*}{dt^*}$  from equation (C.1)?

Note that if  $x^* = \alpha x$  then  $x = \frac{x^*}{\alpha}$ . Thus

$$\begin{aligned} \frac{dx}{dt} &= \frac{d}{dt} \left( \frac{x^*}{\alpha} \right), \\ &= \frac{1}{\alpha} \frac{dx^*}{dt}. \end{aligned}$$

In the scaled equations  $x$  is a function of  $t$  and in the unscaled equations  $x^*$  will be a function of  $t^*$ . Thus the last equation is really,

$$\frac{dx}{dt} = \frac{1}{\alpha} \frac{dx^*(t^*)}{dt}.$$

Note that  $x^*$  is a function of  $t^*$ . It is *not* a function of  $t$ . Thus using the chain rule we obtain

$$\begin{aligned} \frac{dx}{dt} &= \frac{1}{\alpha} \frac{dx^*}{dt^*} \cdot \frac{dt^*}{dt}, \\ &= \frac{1}{\alpha} \frac{dx^*}{dt^*} \cdot \frac{d\beta t}{dt}, \\ &= \frac{\beta}{\alpha} \frac{dx^*}{dt^*}. \end{aligned}$$

Thus the differential equation C.1 becomes

$$\begin{aligned}\frac{dx}{dt} &= f(x), \\ \frac{\beta}{\alpha} \frac{dx^*}{dt^*} &= f\left(\frac{x^*}{\alpha}\right), \\ \frac{dx^*}{dt^*} &= \frac{\alpha}{\beta} f\left(\frac{x^*}{\alpha}\right).\end{aligned}$$

**Example C.1** Show that by introducing variables  $S^* = S/K_s$ ,  $X^* = X/(\alpha K_s)$  and  $t^* = \mu_m t$  the system of differential equations

$$\begin{aligned}V \frac{dS}{dt} &= F(S_0 - S) - V \frac{\mu_m SX}{\alpha(K_s + S)} \\ V \frac{dX}{dt} &= F(X_0 - X) + V \frac{\mu_m SX}{K_s + S},\end{aligned}\tag{C.2}$$

can be written in the scaled form

$$\begin{aligned}\frac{dS^*}{dt^*} &= \frac{1}{\tau^*} (S_0^* - S^*) - \frac{X^* S^*}{1 + S^*}, \\ \frac{dX^*}{dt^*} &= \frac{1}{\tau^*} (X_0^* - X^*) + \frac{X^* S^*}{1 + S^*},\end{aligned}$$

where the scaled parameters are:  $S_0^* = S_0/K_s$ ,  $X_0^* = X_0/(\alpha K_s)$ , and  $\tau_1^* = \mu_m \frac{V}{F}$ .

The system of equations (C.2) is introduced in chapter 4 as a simple model for a bioreactor.

**Solution** Left for the student to do.

## C.2 Questions

1. The Smith population model [22] is given by

$$\frac{dx}{dt} = \frac{r(K-x)}{K+ax}x,$$

where  $a$ ,  $r$  and  $K$  are all positive constants.

What is the corresponding differential equation for the scaled variables  $x^* = \frac{x}{K}$  and  $t^* = rt$ .

2. Consider the population model

$$\frac{dx}{dt} = rx \left(1 - \frac{x}{K}\right) \left(\frac{x}{K_0} - 1\right),$$

where  $r > 0$  and  $0 < K_0 < K$ .

What is the corresponding differential equation for the scaled variables  $x^* = \frac{x}{K}$  and  $t^* = rt$ .

3. The transmission dynamics of a disease in a population is represented by the equation

$$\frac{dI}{dt} = \beta I \left(1 - \frac{I}{K}\right) - \alpha I,$$

where  $I$  is the number of infected individuals in the population,  $\beta$  denotes the transmission coefficient ( $\beta > 0$ ),  $K$  is the total population size ( $K > 0$ ), and  $\alpha$  is the recovery rate ( $\alpha \geq 0$ ).

- (a) Show that the corresponding differential equation for the scaled variables  $I^* = \frac{I}{K}$  and  $t^* = \beta t$  can be written as

$$\frac{dI^*}{dt^*} = (1 - I^*) I^* - \lambda I^*$$

and define the parameter  $\lambda$  in terms of the parameters  $\alpha$ ,  $\beta$  and  $K$ .

- (b) Determine the steady-state solutions and their stability as a function of the parameter  $\lambda$ .
- (c)
  - (i) Draw a steady-state diagram showing how the steady-state solutions and their stability vary as a function of the parameter  $\lambda$ .
  - (ii) Identify the type of bifurcation that occurs in this model.
  - (iii) Explain the physical significance of the value of the parameter  $\lambda$ , relating your discussion to the value of this parameter at the bifurcation value.

4. The Nisbet & Gurney population model [19] is given by

$$\frac{dx}{dt} = \left( r \exp \left[ 1 - \frac{x}{K} \right] \right) - d,$$

where the parameters  $d$ ,  $r$  and  $K$  are all positive.

- (a) Show that the corresponding differential equation for the scaled variables  $x^* = \frac{x}{K}$  and  $t^* = dt$  can be written as

$$\frac{dx^*}{dt^*} = (\lambda \exp [1 - x^*] - 1) x^*$$

and define the parameter  $\lambda$  in terms of the parameters  $d$ ,  $r$  and  $K$ .

- (b) Determine the steady-state solutions and their stability as a function of the parameter  $\lambda$ .
- (c)
  - (i) Draw a steady-state diagram showing how the steady-state solutions and their stability vary as a function of the parameter  $\lambda$ .
  - (ii) Identify the type of bifurcation that occurs in this model.
  - (iii) Explain the physical significance of the value of the parameter  $\lambda$ , relating your discussion to the value of this parameter at the bifurcation value.



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